

# Applications:

$$\begin{array}{c}
 A \\
 \left[ \begin{array}{c} a_1 \cdots a_n \end{array} \right]
 \end{array}
 \begin{array}{c}
 x \\
 \left[ \begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \right]
 \end{array}
 = \underbrace{x_1 a_1 + \cdots + x_n a_n}$$

audio  
 time  
 signal

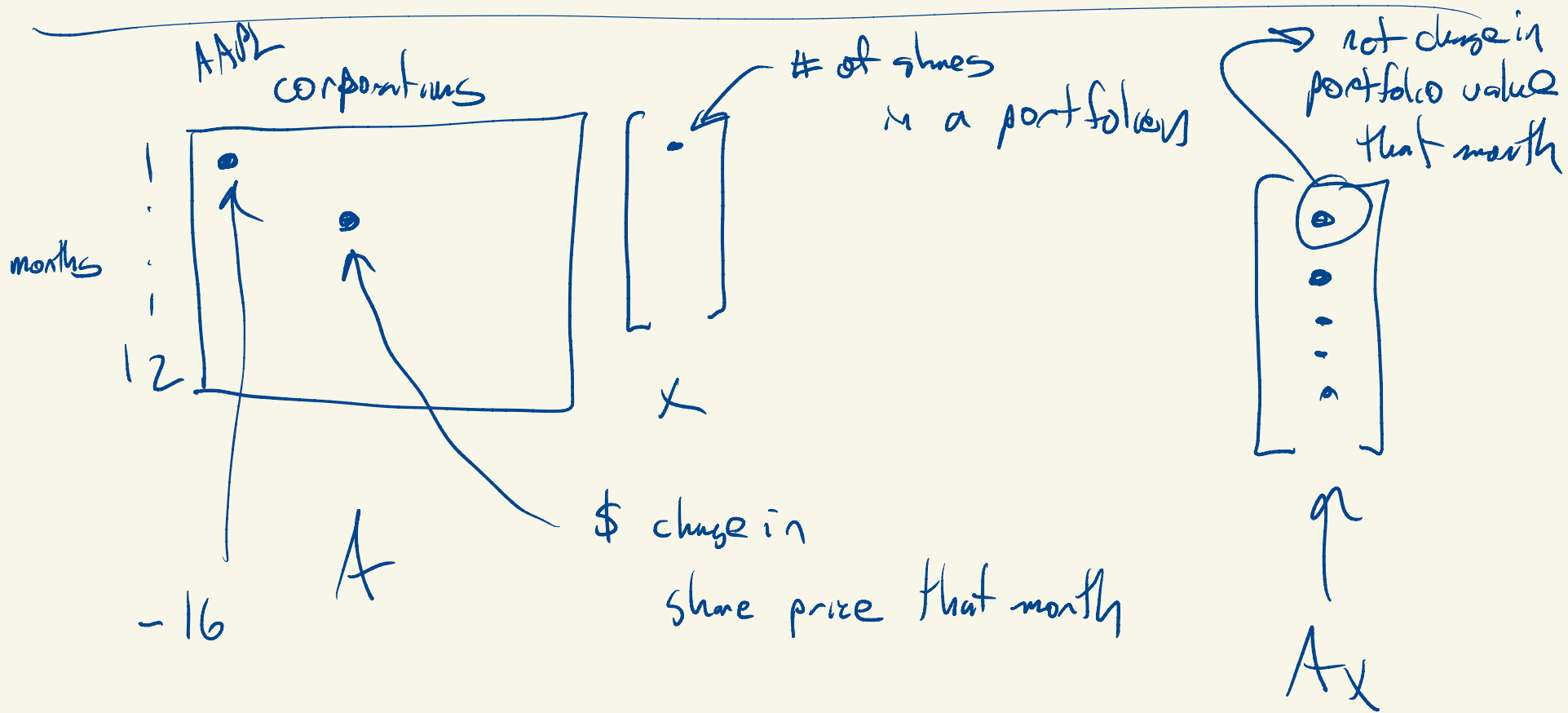
audio

$$\begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix} = \frac{1}{2} a_1 + \frac{1}{2} a_2 = \frac{1}{2} (a_1 + a_2)$$

$$\begin{array}{c}
 n \\
 \left[ \begin{array}{cccc}
 -1 & 1 & 0 & \cdots & 0 \\
 0 & -1 & 1 & 0 & \cdots & 0 \\
 0 & 0 & -1 & 1 & 0 & \cdots & 0 \\
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\
 0 & \cdots & \cdots & 0 & -1 & 1
 \end{array} \right]
 \end{array}
 \begin{array}{c}
 n+1 \\
 \left[ \begin{array}{c} x_1 \\ x_2 \\ \vdots \\ x_{n+1} \end{array} \right]
 \end{array}
 =
 \begin{array}{c}
 \left[ \begin{array}{c} x_2 - x_1 \\ x_3 - x_2 \\ \vdots \\ x_{n+1} - x_n \end{array} \right]
 \end{array}$$

"discrete derivative"

↑  
temperatures at 1 minute intervals



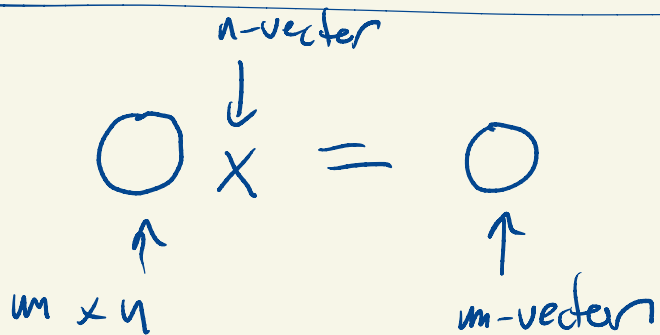
$t_1, t_2, \dots, t_m$

$$\begin{bmatrix} 1 & t_1 & t_1^2 & \dots & t_1^n \\ 1 & t_2 & t_2^2 & \dots & t_2^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_m & t_m^2 & \dots & t_m^n \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} c_0 + c_1 t_1 + c_2 t_1^2 + \dots + c_n t_1^n \\ c_0 + c_1 t_2 + c_2 t_2^2 + \dots + c_n t_2^n \\ \vdots \\ c_0 + c_1 t_m + \dots + c_n t_m^n \end{bmatrix}$$

Vandermonde matrix

$$p(t) = c_0 + c_1 t + \dots + c_n t^n$$

$$\begin{bmatrix} p(t_1) \\ p(t_2) \\ \vdots \\ p(t_m) \end{bmatrix}$$



$$I x = x$$

$\nearrow$   
 $n \times n$

$\nearrow$   
 $n$ -vector

$$I = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

$$I = [e_1 \ e_2 \ \dots \ e_n]$$

$I$  acts like the number 1 for multiplication

$$I x = [e_1 \ \dots \ e_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 e_1 + x_2 e_2 + \dots + x_n e_n = x$$

$$A e_k = [a_1 \ a_2 \ \dots \ a_n] \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow \text{slot } k$$

$\leftarrow$   $k^{\text{th}}$  column of  $A$

$$= 0 \cdot a_1 + 0 a_2 - \dots - 1 a_k + \dots + 0 a_n = a_k$$

$$\vec{1} \quad A \vec{1} = \begin{bmatrix} a_1 & \dots & a_n \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = 1a_1 + 1a_2 + \dots + 1a_n$$

$\uparrow$   $\uparrow$   
 $m \times n$   $n$  vector

$= a_1 + a_2 + \dots + a_n$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 4 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 5 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} 1+2+3 \\ 4+5+6 \end{bmatrix}$$

rules for linear functions

$$A(x+y) = A_x + A_y$$

$$A(cx) = c(A_x)$$

$$A(\alpha x + \beta y) = A(\alpha x) + A(\beta y) \\ = \alpha(A_x) + \beta(A_y)$$

"superposition"

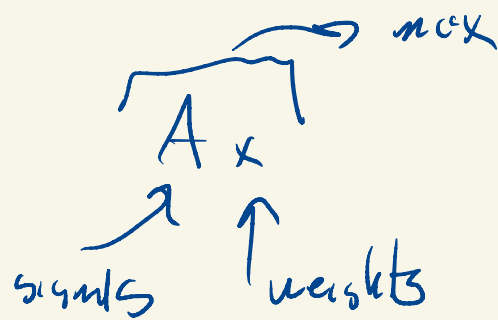
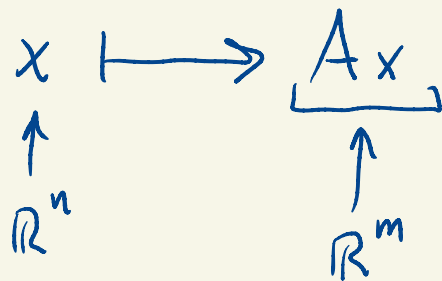
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$$(A+B)_x = A_x + B_x$$

$$(cA)_x = c(A_x)$$

Given a  $m \times n$  matrix  $A$

we have an associated map  $\mathbb{R}^n \rightarrow \mathbb{R}^m$



- e.g:
- share price changes  $\rightarrow$  portfolio <sup>value</sup> not change by nearly
  - audio signals  $\rightarrow$  mixed signal
  - I vector  $\rightarrow$  some thing

$\Theta$ , angle

$$R_{\theta} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

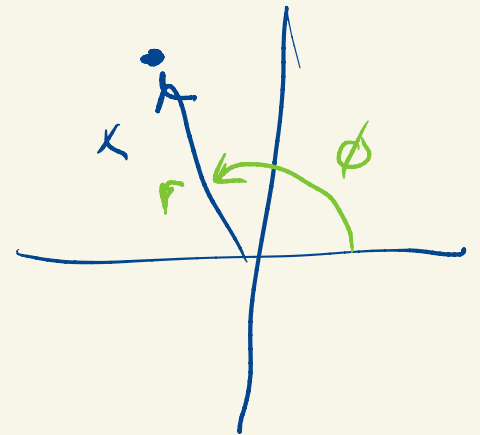
$$R_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$x = \begin{bmatrix} r \cos \phi \\ r \sin \phi \end{bmatrix}$$

$$\cos(A+B) = \cos(A)\cos(B) - \sin(A)\sin(B)$$

$$\sin(A+B) = \cos(A)\sin(B) + \cos(B)\sin(A)$$

$$R_{\theta} x = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} r \cos \phi \\ r \sin \phi \end{bmatrix}$$



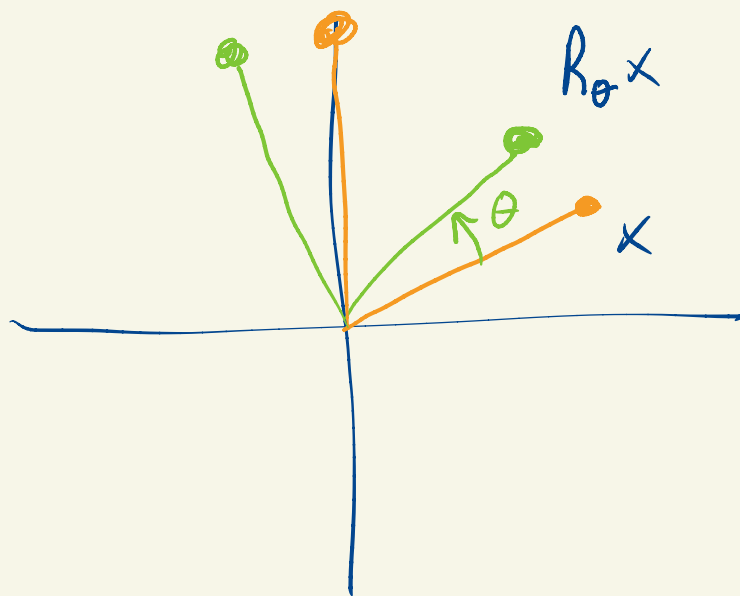


$$= r \begin{bmatrix} \cos \theta \cos \phi - \sin \theta \sin \phi \\ \sin \theta \cos \phi + \cos \theta \sin \phi \end{bmatrix}$$

$$= r \begin{bmatrix} \cos(\phi + \theta) \\ \sin(\phi + \theta) \end{bmatrix}$$

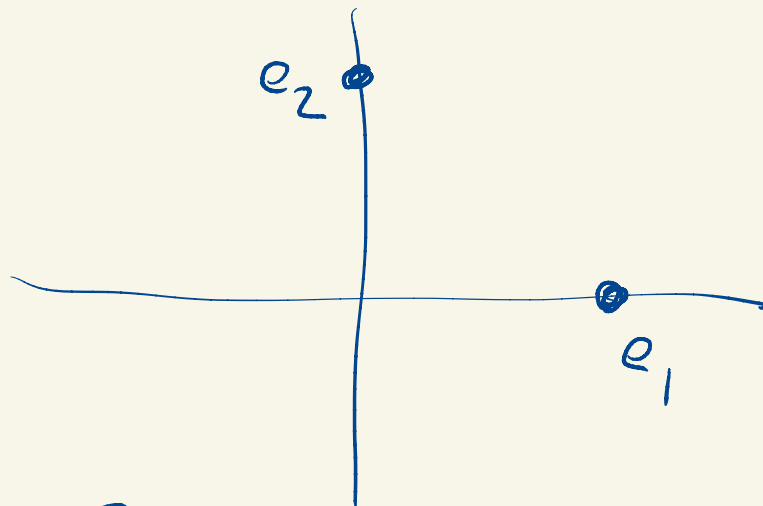
$$x = r \begin{bmatrix} \cos \phi \\ \sin \phi \end{bmatrix} \quad R_{\theta} x = r \begin{bmatrix} \cos(\phi + \theta) \\ \sin(\phi + \theta) \end{bmatrix}$$

$R_{\theta}$  represents rotation of the plane  
by angle  $\theta$



$$x \mapsto R_\theta x$$

rotate  $x$  by angle  $\theta$ .



$$R_{\pi/2} = \begin{bmatrix} \cos(\pi/2) & -\sin(\pi/2) \\ \sin(\pi/2) & \cos(\pi/2) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$R_{\pi/2} e_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = e_2$$

$$R_{\pi/2} e_2 = \begin{bmatrix} -1 \\ 0 \end{bmatrix} = -e_1$$

$$x \pm \bar{y}$$

$$\begin{bmatrix} x & -y \\ y & x \end{bmatrix}$$