

$a, b, c, d \in \mathbb{R}$

↑ iff

$$\frac{az + b}{cz + d} = \frac{az + b}{cz + d} \frac{\overline{cz + d}}{\overline{cz + d}} = \frac{ac|z|^2 + bc\bar{z} + adz + bd}{|cz + d|^2}$$

$$= \frac{ac|z|^2 + bd}{|cz + d|^2} + \frac{adz + bc\bar{z}}{|cz + d|^2}$$

$z = x + iy$

$$\frac{(adx + bcx) + iy(ad - bc)}{|cz + d|^2}$$

imaginary part is $i y \frac{(ad-bc)}{|cz+d|^2}$

upper half plane maps to upper half plane $\Leftrightarrow ad-bc > 0$

$y > 0$

$z \rightarrow \bar{z}$

$Tz = \frac{az+b}{cz+d}$

$a, b, c, d \in \mathbb{R}$

$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$

$ad-bc > 0$

WLOG $(ad-bc = 1)$



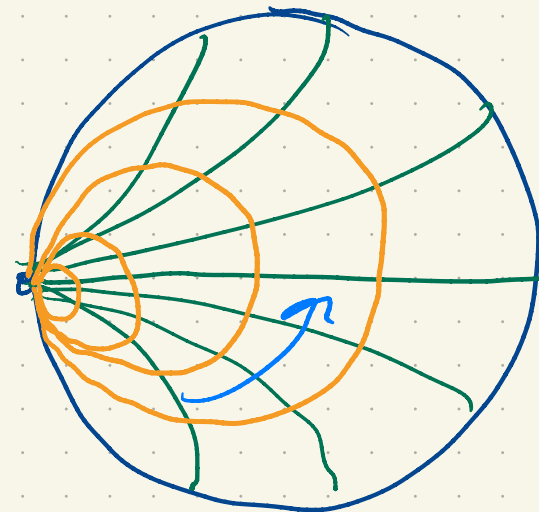
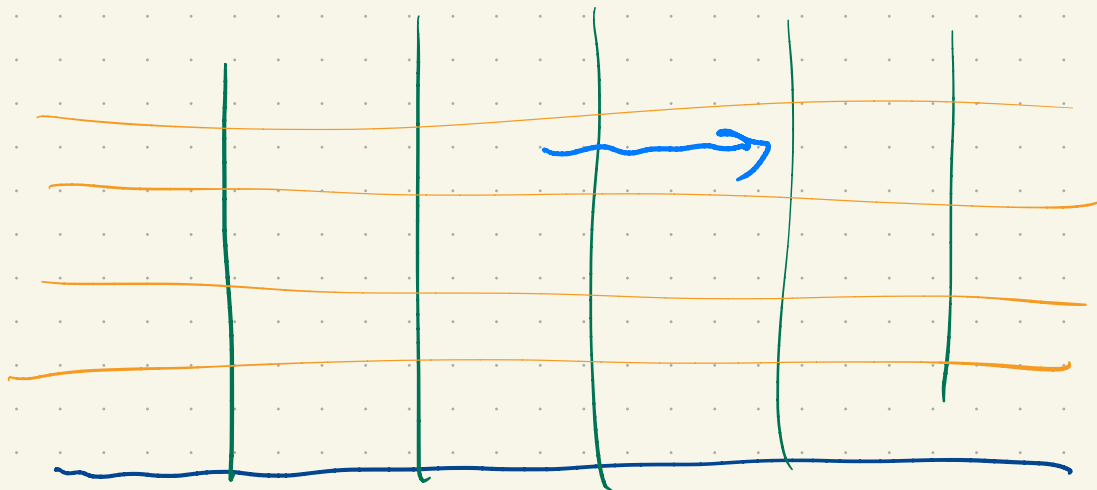
$Tz = \lambda \frac{z-p}{1-\bar{p}z}$ $\lambda \in \mathbb{S}^1, p \in \mathbb{D}$

$$T_z = \frac{az+b}{cz+d}$$

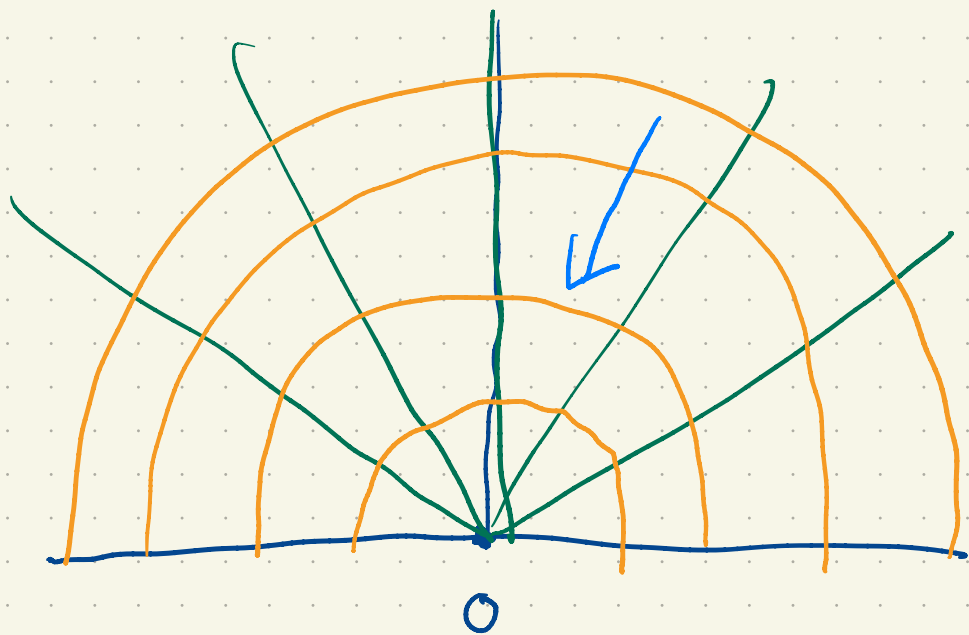
$$a=1, b, c=0, d=1$$

$$ad-bc = 1 \cdot 1 - b \cdot 0 = 1$$

$$T_z = z + b \quad \xrightarrow{\text{R}}$$

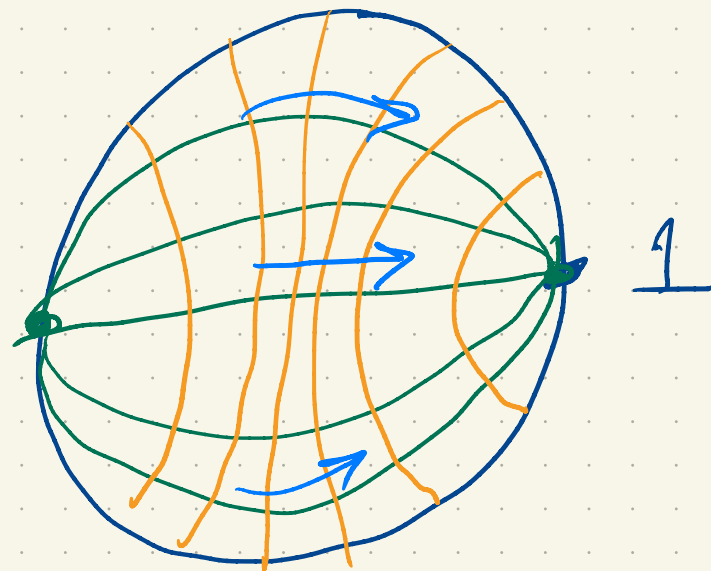


$$Tz = az \quad \text{if } a > 0$$



$$a, b=0, c=0, d=1$$

$$ad - bc = ad = a > 0$$



Translation →

Rotations about i

$\bullet i$

$$T_z$$
$$T\bar{z} = \bar{z}$$
$$\rightarrow \frac{az+b}{cz+d}$$

$$a = d$$

$$b = -c$$

$$T_z = \frac{(az+b)\lambda}{(-bz+a)\lambda}$$

$$T\bar{z} = \bar{z}$$

$$\frac{a\bar{z}+b}{c\bar{z}+d} = \bar{z}$$

$$a\bar{z}+b = -c + d\bar{z}$$

$$a, b, c, d \in \mathbb{R}$$

$$\sqrt{a^2 + b^2} > 0$$

$$\lambda = \frac{1}{\sqrt{a^2 + b^2}}$$

$$a^2 + b^2 = 1$$

$$a = \cos(\theta/2) \quad b = \sin(\theta/2)$$

$$\begin{bmatrix} \cos(\theta/2) & \sin(\theta/2) \\ -\sin(\theta/2) & \cos(\theta/2) \end{bmatrix}$$

$$\sin(\psi + \pi) = -\sin(\psi)$$

$$\cos(\psi + \pi) = -\cos(\psi)$$

$$\cos\left(\frac{\theta + 2\pi}{2}\right) = \cos\left(\frac{\theta}{2} + \pi\right) = -\cos\left(\frac{\theta}{2}\right)$$

$$\sin\left(\frac{\theta + 2\pi}{2}\right) = -\sin\left(\frac{\theta}{2}\right)$$

$$Tz = \frac{az + b}{-bz + a}$$

$$\theta = \pi/2$$

$$\cos(\theta/2) = \cos(\pi/4) = 1/\sqrt{2}$$

$$\sin(\theta/2) = \sin(\pi/4) = 1/\sqrt{2}$$

$$Tz = \frac{z+1}{-z+1}$$

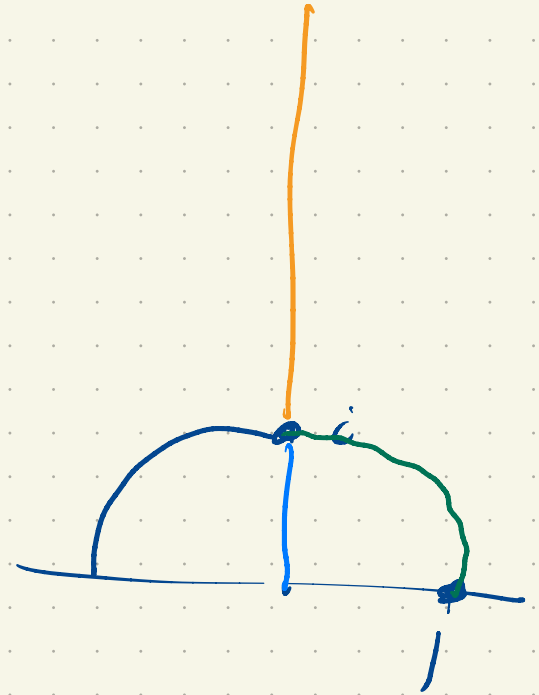
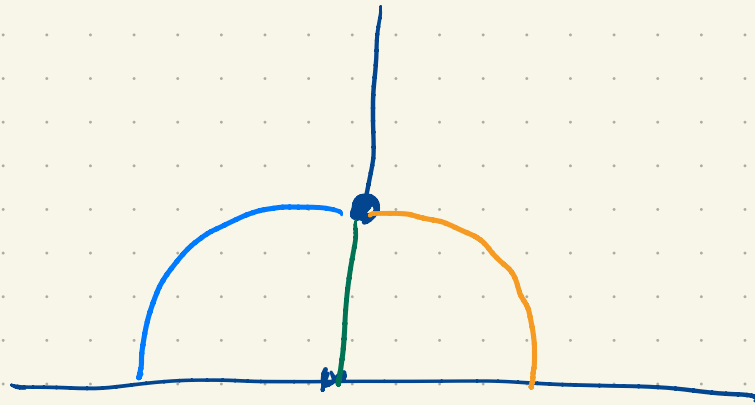
$$T(i) = i$$

$$T(0) = 1$$

$$T(1) = \infty$$

$$T(\infty) = -1$$

$$T(-1) = 0$$



[Exercise: do this again with $\theta = \pi$.