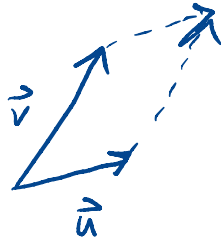


Last class:

$$\begin{vmatrix} \vec{u} \\ \vec{v} \end{vmatrix} = \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} = u_1 v_2 - u_2 v_1$$



Is the area of this parallelogram, up to sign.

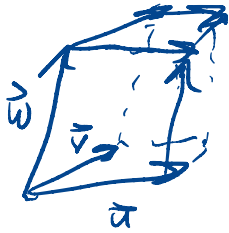
$> 0 \Rightarrow$ turn left from \vec{u} to \vec{v}

$< 0 \Rightarrow$ turn right

$= 0 \Rightarrow ?$ \vec{u} and \vec{v} are colinear.

$$\begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} = u_1 \begin{vmatrix} v_2 & v_3 \\ w_2 & w_3 \end{vmatrix} - u_2 \begin{vmatrix} v_1 & v_3 \\ w_1 & w_3 \end{vmatrix} + u_3 \begin{vmatrix} v_1 & v_2 \\ w_1 & w_2 \end{vmatrix}$$

Equals, up to sign, volume of:



positive if curl fingers (right-hand) \vec{a} to \vec{b}
has thumb on same side as \vec{w} .

Introduced $\vec{a} \times \vec{b}$, a vector.

$$\vec{a} \times \vec{a} = \vec{0} \quad \forall \vec{a}$$

$$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

$$\vec{a} \cdot (\vec{a} \times \vec{b}) = 0$$

$$\vec{b} \cdot (\vec{a} \times \vec{b}) = 0$$

($\vec{a} \times \vec{b}$ is perp to \vec{a}, \vec{b})

\vec{a} is perpendicular to $\vec{a} \times \vec{b}$.
↑ geometry!

$$\vec{b} \cdot (\vec{a} \times \vec{b}) = -\vec{b} \cdot (\vec{b} \times \vec{a}) = -0 = 0.$$

\vec{b} is perpendicular to $\vec{a} \times \vec{b}$ also.

Key Property: $\vec{a} \times \vec{b}$ is perpendicular
to both \vec{a} and \vec{b} .

Manemonic for computing, using determinants

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$(a_2 b_3 - a_3 b_2) \vec{i}$$

$$\begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \vec{j}$$

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$(a_3 b_1 - a_1 b_3) \vec{j} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \vec{j}$$

(Note swapped order!)

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

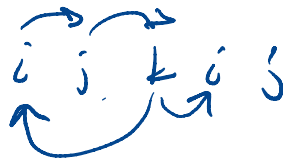
$$(a_1 b_2 - a_2 b_1) \vec{k} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \vec{k}$$

Cross product is sum of all 3.

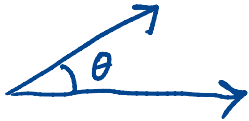
$$\vec{i} \times \vec{j} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = 0\vec{i} + 0\vec{j} + 1\vec{k} = \vec{k}$$

$$\vec{j} \times \vec{k} = \vec{i}$$

$$\vec{k} \times \vec{i} = \vec{j}$$



Recall $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$



$$0 < \theta < \pi$$

$$\vec{a} = |\vec{a}| \vec{i}$$

$$\vec{b} = |\vec{b}| \cos \theta \vec{i} + |\vec{b}| \sin \theta \vec{j}$$

$$\vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin \theta \vec{i} \times \vec{j}$$

$$= |\vec{a}| |\vec{b}| \sin \theta \vec{k}$$

$$|\vec{a} \times \vec{b}| = |\vec{a}| |\vec{b}| \sin \theta$$

This is always true.

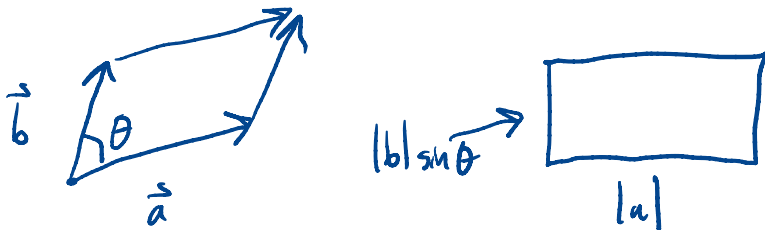
$$\vec{u} = \langle u_1, u_2, 0 \rangle$$

$$\vec{v} = \langle v_1, v_2, 0 \rangle$$

$$\vec{u} \times \vec{v} = (u_1 v_2 - u_2 v_1) \vec{k}$$

↳ this is a 2x2 determinant

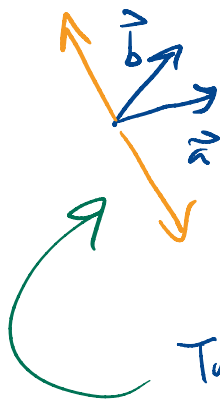
$|\vec{u} \times \vec{v}|$ is area of parallelogram spanned by \vec{u}, \vec{v} ,



$|\vec{a} \times \vec{b}|$ is the area of the parallelogram spanned by \vec{a}, \vec{b} .

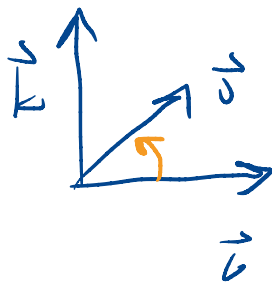
So $\vec{a} \times \vec{b}$ is perp to \vec{a} , and perp to \vec{b} .

We know its length. Great.



Two possibilities.

$$\vec{i} \times \vec{j} = \vec{k}$$



Right hand fingers curl from \vec{a} to \vec{b} , thumb

is on same side as $\vec{a} \times \vec{b}$.

$\vec{a} \times \vec{b} = 0$ means what?

$$|\vec{a}| |\vec{b}| \sin \theta = 0$$

$$\vec{a} = 0 \quad \text{or} \quad \vec{b} = 0 \quad \text{or}$$

$$\sin \theta = 0 \quad 0 \leq \theta \leq \pi$$

$$\Rightarrow \theta = 0, \pi$$

$\vec{a} \times \vec{b} = 0 \Leftrightarrow \vec{a}$ and \vec{b} are colinear.

Algebra rules:

$$\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$$

$$(c\vec{a}) \times \vec{b} = c(\vec{a} \times \vec{b}) = \vec{a} \times (c\vec{b})$$

But:

$$\left. \begin{aligned} \vec{i} \times (\vec{i} \times \vec{j}) &= \vec{i} \times \vec{k} = -\vec{j} \\ (\vec{i} \times \vec{i}) \times \vec{j} &= \vec{0} \times \vec{j} = \vec{0} \end{aligned} \right\} \text{not assoc!}$$

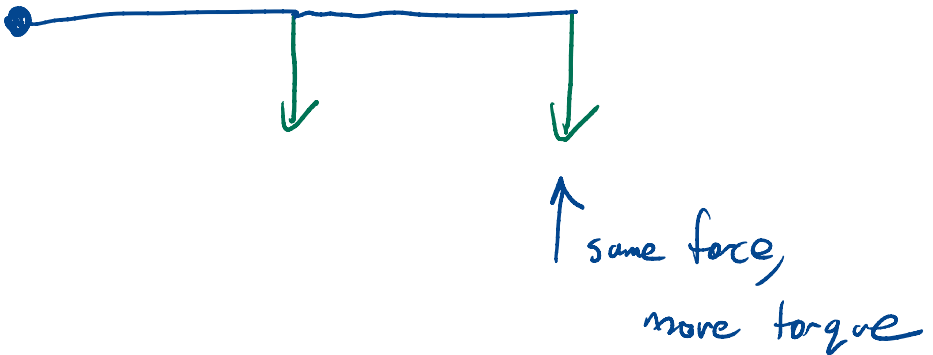
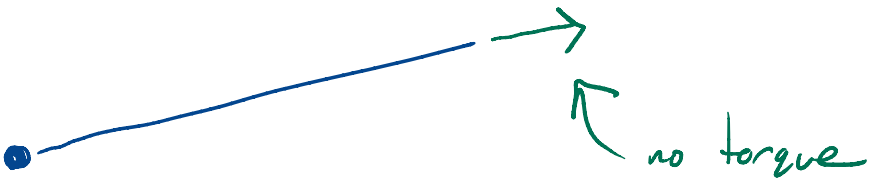
Instead:

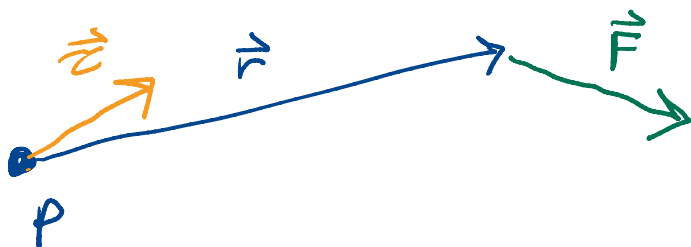
$$\begin{aligned} \vec{a} \times (\vec{b} \times \vec{c}) &= \alpha \vec{b} + \beta \vec{c} \\ &= (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c} \end{aligned}$$

$$\vec{i} \times (\vec{i} \times \vec{j}) = \vec{i} \times \vec{k} = -\vec{j}$$

$$(\vec{i} \cdot \vec{j}) \vec{i} - (\vec{i} \cdot \vec{i}) \vec{j} = -\vec{j} \checkmark$$

Torque: (A vector!)





By definition, the torque at P of \vec{F}

is $\vec{r} \times \vec{F} = \vec{z}$ (Units: Nm ,
newton metres)



If \vec{F} is parallel to \vec{r} $\vec{r} \times \vec{F} = \vec{0}$

$$|\vec{r} \times \vec{F}| = |\vec{r}| |\vec{F}| \sin \theta$$

maximised when $\theta = \frac{\pi}{2}$



Determine the size of the torque vector:
and direction

$$\vec{F} = 100 \text{ N} \cos(70^\circ) \hat{z} - 100 \text{ N} \sin(70^\circ) \hat{y}$$

$$0.3 \text{ m} \hat{z} \times \vec{F} =$$

$$-0.3 \cdot 100 \text{ Nm} \sin(70^\circ) \hat{z} \times \hat{y}$$

$$-28.19 \text{ Nm} \hat{k}$$

28.2 Nm into page

Triple Product

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

Just a
computation.

$$= - \begin{vmatrix} a_3 & b_3 & c_3 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}$$

$$= + \begin{vmatrix} a_2 & b_2 & c_2 \\ a_1 & b_1 & c_1 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

$$= \vec{c} \cdot (\vec{a} \times \vec{b})$$

$$= (\vec{a} \times \vec{b}) \cdot \vec{c}$$

If you believed me about volume of parallelepiped, up to sign, this gives geometric meaning to the triple product.