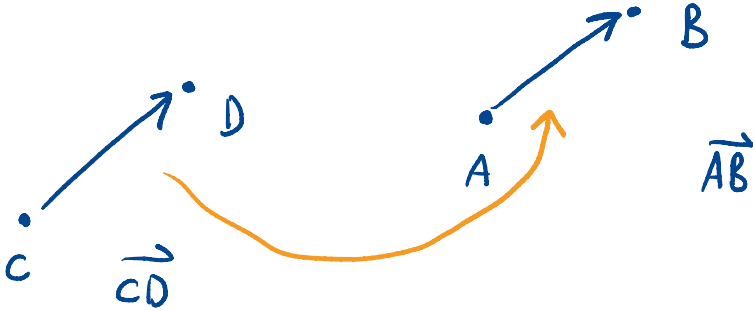


Section 12.2

Displacement Vectors

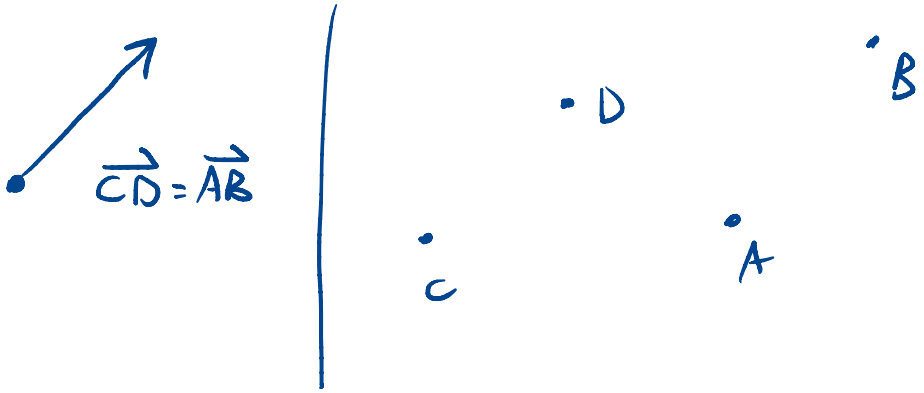


The displacements from C to D and from A to B are the same.

If we translate C to A then D lands on B.

We identify:

$$\vec{CD} = \vec{AB}$$



↑
Land of vectors
(displacements)

↑
Euclidean space
(points)

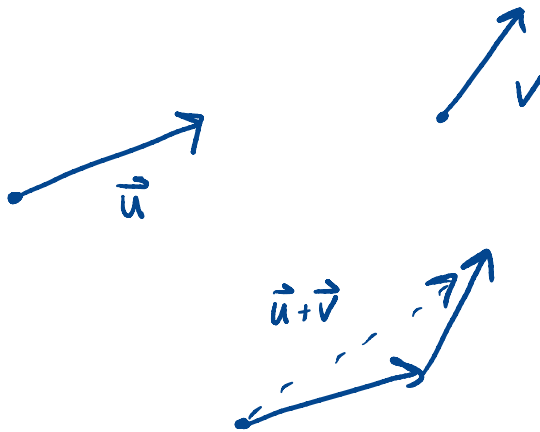
Displacement vectors have a direction
(mostly) and a length.

$|\vec{AB}|$ is just the distance from A to B.

The zero vector does not have a direction.

Operations on vectors:

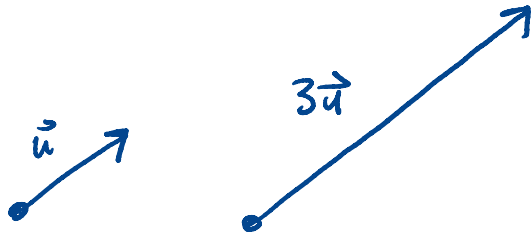
1) Vector addition



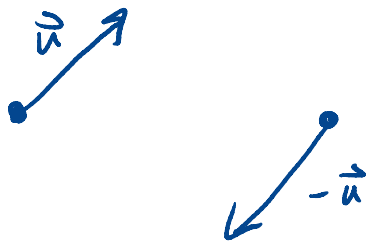
$$\vec{AB} + \vec{BC} = \vec{AC}$$

2) Scalar multiplication: $a > 0, \vec{u} \neq 0$

$a\vec{u}$ is the vector parallel to \vec{u}
with length $a|\vec{u}|$



$a < 0$: points in opposite directions

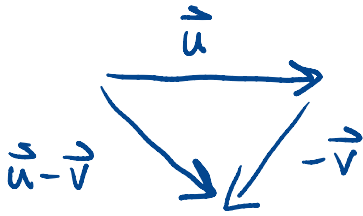


$a \cdot \vec{0} = \vec{0}$ no matter what a is.

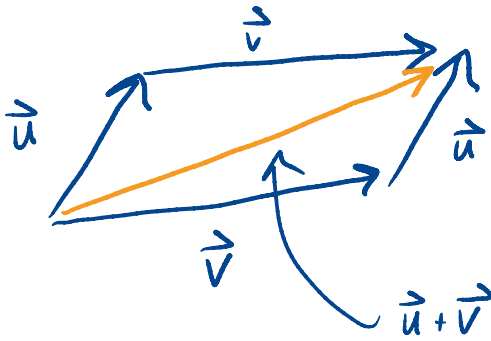
3) Subtraction

$$\vec{u} - \vec{v} = \vec{u} + (-\vec{v})$$





Addition is commutative



The zero vector is special:

$$\vec{0} + \vec{u} = \vec{u} + \vec{0} \quad \text{no matter what } \vec{u} \text{ is.}$$

Note: the origin of your coordinate system
Cartesian is arbitrary.

The zero vector (zero displacement!)
is a very real thing.

Once you establish \wedge coordinates, \wedge vectors gain
Cartesian displacement
coordinates as well:

$$P(x_0, y_0, z_0)$$

$$Q(x_1, y_1, z_1)$$

$$\vec{PQ} = \langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle$$

↳ not standard, but used in text

It's just the difference in coordinates.

The geometric vector operations have
very natural algebraic equivalents:

$$\vec{a} = \langle a_1, a_2, a_3 \rangle$$

$$\vec{b} = \langle b_1, b_2, b_3 \rangle$$

$$\vec{a} + \vec{b} = \langle a_1 + b_1, a_2 + b_2, a_3 + b_3 \rangle$$

$$c\vec{a} = \langle ca_1, ca_2, ca_3 \rangle$$

$$\vec{a} - \vec{b} = \langle a_1 - b_1, a_2 - b_2, a_3 - b_3 \rangle$$

Properties:

$$(\vec{a} + \vec{b}) + \vec{c} = \vec{a} + (\vec{b} + \vec{c})$$

$$c(\vec{a} + \vec{b}) = c\vec{a} + c\vec{b}$$

$$(c+d)\vec{a} = c\vec{a} + d\vec{a}$$

$$c(d\vec{a}) = (cd)\vec{a}$$

$$\vec{a} + 0 = \vec{a} \quad | \quad 1\vec{a} = \vec{a}$$

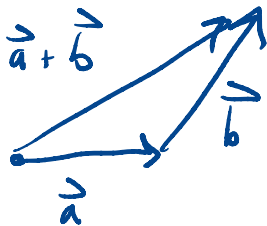
The length of a vector is the
Euclidean length of the displacement

$$|\vec{a}| = \sqrt{a_1^2 + a_2^2 + a_3^2}$$

$$\left(\sqrt{(\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2} \right)$$

$$|c\vec{a}| = |c| |\vec{a}|$$

$$|\vec{a} + \vec{b}| = |\vec{a}| + |\vec{b}|? \text{ Nope.}$$



$$|\vec{a} + \vec{b}| \leq |\vec{a}| + |\vec{b}|$$

Common operation:

$$\vec{u} = \langle \sqrt{5}, 2, 4 \rangle$$

$$|\vec{u}|^2 = 5 + 4 + 16 = 25$$

$$|\vec{u}| = 5$$

$$\frac{1}{5} \vec{u} = \left\langle \frac{\sqrt{5}}{5}, \frac{2}{5}, \frac{4}{5} \right\rangle$$



$$\left| \frac{1}{5} \vec{u} \right| = \left| \frac{1}{5} \right| |\vec{u}| = \frac{1}{5} \cdot 5 = 1$$

We say $\frac{1}{5} \vec{u}$ is a unit vector.

It points parallel to \vec{u} but has unit

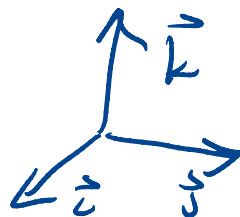
length.

We give names to three unit vectors that point along the coordinate axes:

$$\vec{i} = \langle 1, 0, 0 \rangle$$

$$\vec{j} = \langle 0, 1, 0 \rangle$$

$$\vec{k} = \langle 0, 0, 1 \rangle$$



(standard basis vectors)

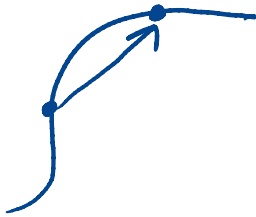
These depend on your coordinates.

0 is special. \vec{i} is not.

$$\begin{aligned}\vec{a} &= \langle a_1, a_2, a_3 \rangle \\ &= a_1 \vec{i} + a_2 \vec{j} + a_3 \vec{k}.\end{aligned}$$

Other vectorial quantities

- velocity (m/s)
 - acceleration (m/s^2)
 - force ($\text{kg m/s}^2 = \text{N}$)
- The other parts are "decoration"

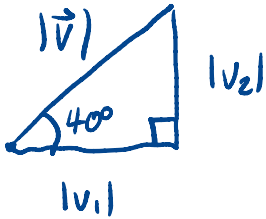
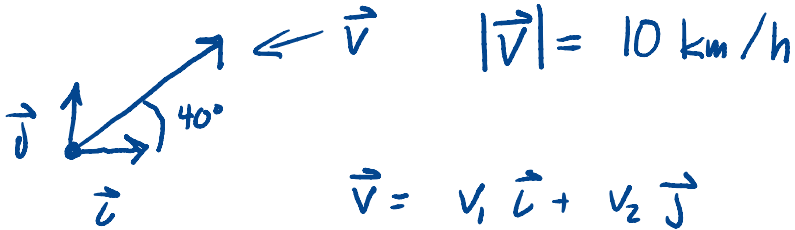


$$\frac{\vec{a}(t_1) - \vec{a}(t_0)}{t_1 - t_0} \quad \frac{\text{dist}}{\text{time}}$$

send $t_1 \rightarrow t_0$ and get an instantaneous velocity.

All the rules thus far also apply to these physical variations of displacement vectors

Components of Physical vectors



$$|v_1| = |\vec{V}| \cos(40^\circ) \approx 7.7$$

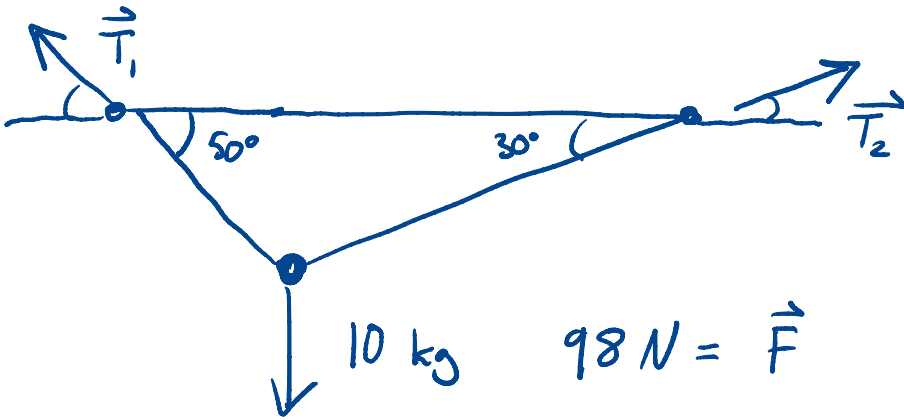
$$|v_2| = |\vec{V}| \sin(40^\circ) \approx 6.4$$

$v_1 > 0$, $v_2 > 0$ also
in this case.

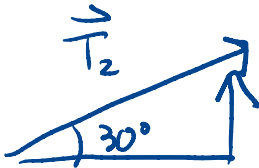
$$\vec{V} \approx 7.7 \vec{i} + 6.4 \vec{j}$$

Forces are especially important

Statics: The sum of forces acting on a body add to zero.



$$\vec{T}_1 + \vec{T}_2 + \vec{F} = 0$$



$$\vec{T}_2 = \cos(30^\circ) |T_2| \vec{i} + \sin(30^\circ) |T_2| \vec{j}$$

$$\vec{T}_1 = -\cos(50^\circ) |\vec{T}_1| \vec{i} + \sin(50^\circ) |\vec{T}_1| \vec{j}$$

$$\vec{F} = -98 \vec{j}$$

\vec{i} component:

$$\cos(30^\circ) |\vec{T}_2| - \cos(50^\circ) |\vec{T}_1| = 0$$

\vec{j} component:

$$\sin(30^\circ) |\vec{T}_2| + \sin(50^\circ) |\vec{T}_1| = 98$$

$$|\vec{T}_2| = \frac{\cos(50^\circ)}{\cos(30^\circ)} |\vec{T}_1|$$

$$\left[\tan(30^\circ) \cos(50^\circ) + \sin(50^\circ) \right] |\vec{T}_1| = 98$$

$$|\vec{T}_1| = 98 / \underbrace{[\tan(30^\circ)\cos(50^\circ) + \sin(50^\circ)]}_{1.137\dots = a}$$

$$|\vec{T}_1| = 86.1797\dots$$

$$|\vec{T}_2| = \frac{\cos(50^\circ)}{\cos(30^\circ)} |\vec{T}_1|$$

$$|\vec{T}_2| = 63.96\dots$$

$$\vec{T}_1 = -\cos(50^\circ)|\vec{T}_1|\vec{i} + \sin(50^\circ)|\vec{T}_1|\vec{j}$$

$$\approx -55.395\vec{i} + 66.017\vec{j}$$

$$\vec{T}_2 \approx -55.395\vec{i} + 31.18\vec{j}$$