

## Alternative Approach

Suppose we can find  $\mathbf{q}_1, \dots, \mathbf{q}_m$  that satisfy  $\mathbf{q}_i \cdot \mathbf{q}_j = \delta_{ij}$  and such that

$$A = [\mathbf{q}_1 \dots \mathbf{q}_m]R$$

for an invertible upper triangular matrix  $R$ .

$$\rightarrow \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

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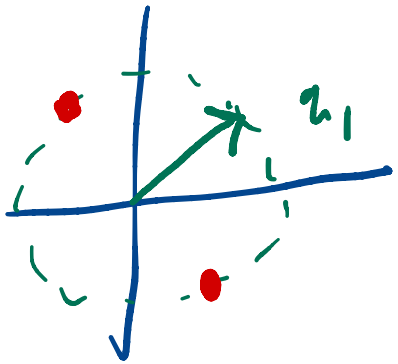
$$A = [\mathbf{q}_1 \dots \mathbf{q}_m] R$$

for an invertible upper triangular matrix  $R$ .

QR factorization

$$Q = [\mathbf{q}_1 \dots \mathbf{q}_m]; \quad Q^T Q = I$$

$$\rightarrow A = QR$$

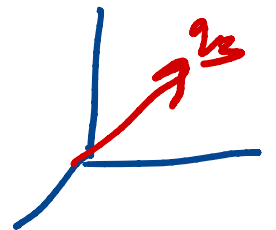


$$q_3 \cdot q_3 = 1$$

$$q_3 \cdot q_1 = 0$$

$$q_i \perp q_j \text{ if } i \neq j$$

$$q_3 = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$



$$q_3 \cdot q_3 = a^2 + b^2 + c^2$$

$$\vec{x} \cdot \vec{x} = \|\vec{x}\|_2^2 \quad \leftarrow \text{(length)}^2 \text{ of } \vec{x}$$

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for an invertible upper triangular matrix  $R$ .

$$A \vec{x} = \vec{y}$$

$$A^T A \vec{x} = A^T \vec{y}$$

$$Q = [\mathbf{q}_1 \dots \mathbf{q}_m]; \quad Q^T Q = I$$

$$Q^T \begin{bmatrix} \mathbf{q}_1^T \\ \vdots \\ \mathbf{q}_m^T \end{bmatrix} \begin{bmatrix} \mathbf{q}_1 & \dots & \mathbf{q}_m \end{bmatrix} = \begin{bmatrix} \mathbf{q}_1^T \mathbf{q}_1 & \mathbf{q}_1^T \mathbf{q}_2 & \dots & \mathbf{q}_1^T \mathbf{q}_m \\ \mathbf{q}_2^T \mathbf{q}_1 & \mathbf{q}_2^T \mathbf{q}_2 & \dots & \mathbf{q}_2^T \mathbf{q}_m \\ \vdots & & \ddots & \vdots \\ \mathbf{q}_m^T \mathbf{q}_1 & \mathbf{q}_m^T \mathbf{q}_2 & \dots & \mathbf{q}_m^T \mathbf{q}_m \end{bmatrix}$$

$$A = QR$$

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for an invertible upper triangular matrix  $R$ .

$$Q = [\mathbf{q}_1 \dots \mathbf{q}_m]; \quad Q^T Q = I$$

Normal equation:

$$A^T A \mathbf{x} = A^T \mathbf{b}$$

Becomes

$$(QR)^T (QR) \mathbf{x} = (QR)^T \mathbf{b}$$

$$\begin{aligned} A &= QR \\ A^T &= (QR)^T \\ &= R^T Q^T \end{aligned}$$

$$\Rightarrow R^T Q^T Q R \vec{x} = R^T Q^T \vec{b}$$

$$R^T R \vec{x} = R^T Q^T \vec{b}$$

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for an invertible upper triangular matrix  $R$ .

$$Q = [\mathbf{q}_1 \dots \mathbf{q}_m]; \quad Q^T Q = I$$

$$\begin{array}{ll} Q & n \times n \\ R & n \times m \end{array}$$

Normal equation:

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Becomes

$$(QR)^T (QR) \mathbf{x} = (QR)^T \mathbf{b}$$

Then

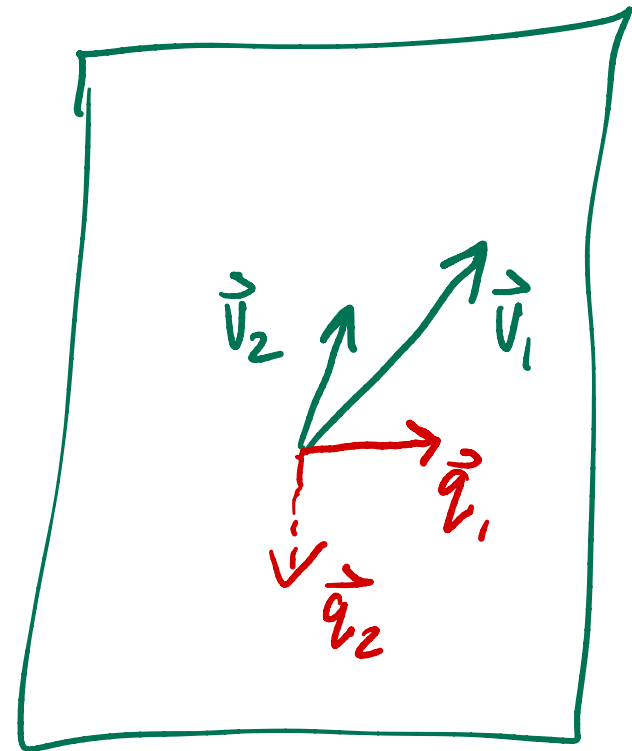
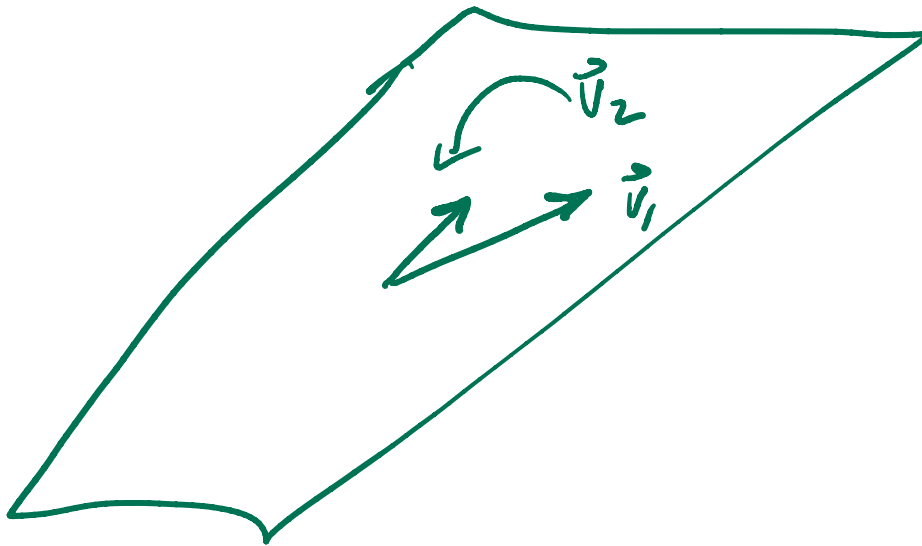
$$O(n^2) \quad R \mathbf{x} = Q^T \mathbf{b} \quad O(n^2) \quad O(n^2)$$

We avoid forming  $A^T A$  or anything that looks like a square of  $A$ .

# Gramm-Schmidt

Vectors  $\mathbf{v}_1, \mathbf{v}_2$ , linearly independent.

Goal: Find perpendicular unit vectors  $\mathbf{q}_1, \mathbf{q}_2$  such that the span of the  $\mathbf{v}$ 's is the same as the span of the  $\mathbf{q}$ 's.



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$$\tilde{\mathbf{q}}_1 = \mathbf{v}_1$$
$$\mathbf{q}_1 = \tilde{\mathbf{q}}_1 / \|\tilde{\mathbf{q}}_1\|_2$$

ensures  $\vec{q}_i \cdot \vec{q}_i = 1$



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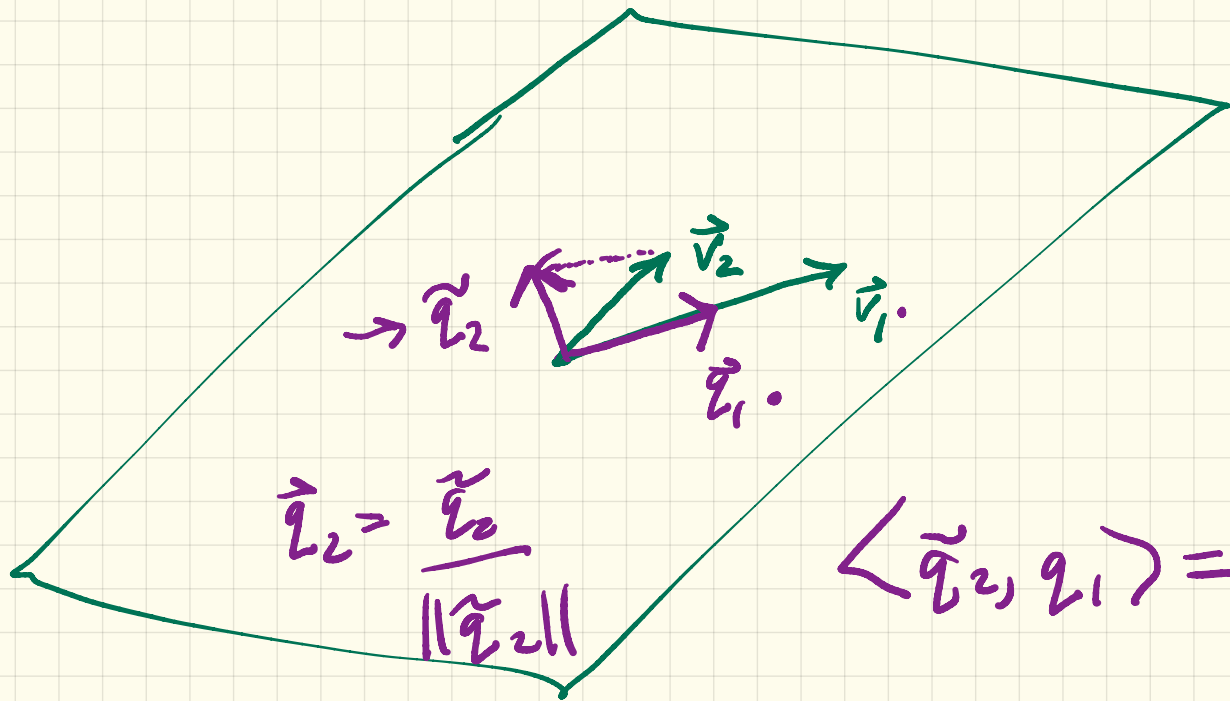
$$\mathbf{q}_1 = \tilde{\mathbf{q}}_1 / \|\tilde{\mathbf{q}}_1\|_2$$

$$r_{11} = \|\tilde{\mathbf{q}}_1\|_2$$

$$\mathbf{v}_1 = r_{11}\mathbf{q}_1$$

$$\vec{q}_1 = \vec{v}_1 / \|\vec{v}_1\|_2$$

$$\vec{v}_1 = \|\vec{v}_1\|_2 \cdot \vec{q}_1$$



$$\vec{q}_1 = \frac{\vec{v}_2 \cdot \vec{v}_1}{\|\vec{v}_1\|}$$

$$\langle \tilde{q}_2, q_1 \rangle = 0$$

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Already found  $\mathbf{q}_1, r_{11}$

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$$\tilde{\mathbf{q}}_2 = \mathbf{v}_2 - \langle \mathbf{q}_1, \mathbf{v}_2 \rangle \mathbf{q}_1$$

$q_1^T v_2$   
 $q_1 \cdot v_2$   
 $\langle q_1, v_2 \rangle$

$$\begin{aligned}\langle \tilde{\mathbf{q}}_2, \mathbf{q}_1 \rangle &= \langle \mathbf{v}_2 - \langle \mathbf{q}_1, \mathbf{v}_2 \rangle \mathbf{q}_1, \mathbf{q}_1 \rangle \\ &= \langle \mathbf{v}_2, \mathbf{q}_1 \rangle - \langle \mathbf{q}_1, \mathbf{v}_2 \rangle \underbrace{\langle \mathbf{q}_1, \mathbf{q}_1 \rangle}_{1} \\ &= 0\end{aligned}$$

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$$\mathbf{q}_2 = \tilde{\mathbf{q}}_2 / \|\tilde{\mathbf{q}}_2\|_2$$

$$\tilde{r}_{22} = \|\tilde{\mathbf{q}}_2\|_2 \cdot r_{22}$$

$$\vec{\mathbf{v}}_2 = \overbrace{\langle \mathbf{q}_1, \mathbf{v}_2 \rangle}^{r_{12}} \mathbf{q}_1 + \overbrace{\|\tilde{\mathbf{q}}_2\|_2}^{r_{22}} \mathbf{q}_2$$

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$$\mathbf{q}_2 = \tilde{\mathbf{q}}_2 / \|\tilde{\mathbf{q}}_2\|_2$$

$$\mathbf{v}_2 = \|\tilde{\mathbf{q}}_2\|_2 \mathbf{q}_2 + \langle \mathbf{q}_1, \mathbf{v}_2 \rangle \mathbf{q}_1$$

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$$\mathbf{q}_2 = \tilde{\mathbf{q}}_2 / \|\tilde{\mathbf{q}}_2\|_2$$

$$\mathbf{v}_2 = \|\tilde{\mathbf{q}}_2\|_2 \mathbf{q}_2 + \langle \mathbf{q}_1, \mathbf{v}_2 \rangle \mathbf{q}_1$$

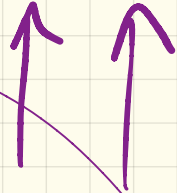
$$r_{12} = \langle \mathbf{q}_1, \mathbf{v}_2 \rangle; \quad r_{22} = \|\tilde{\mathbf{q}}_2\|_2$$



$v_1, v_2$

$[\vec{v}_1, \vec{v}_2]$

$q_1, q_2$



$$v_1 = r_{11} q_1$$

$$v_2 = r_{12} q_1 + r_{22} q_2$$

$$\begin{bmatrix} \vec{q}_1 & \vec{q}_2 \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} \\ 0 & r_{22} \end{bmatrix}$$

$$= \begin{bmatrix} r_{11} \vec{q}_1 + 0 \vec{q}_2 & r_{12} \vec{q}_1 + r_{22} \vec{q}_2 \end{bmatrix}$$

## Gramm-Schmidt: More vectors!

Start with  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ .

Compute  $\mathbf{q}_1, \mathbf{q}_2, r_{11}, r_{12}$  and  $r_{22}$  the same way.

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$$\tilde{\mathbf{q}}_3 = \mathbf{v}_3 - \langle \mathbf{v}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{v}_3, \mathbf{q}_2 \rangle \mathbf{q}_2$$

Want  $\langle \tilde{\mathbf{q}}_3, \mathbf{q}_1 \rangle = 0, \quad \langle \tilde{\mathbf{q}}_3, \mathbf{q}_2 \rangle = 0.$

$$\begin{aligned} \langle \tilde{\mathbf{q}}_3, \mathbf{q}_1 \rangle &= \langle \mathbf{v}_3, \mathbf{q}_1 \rangle - \langle \mathbf{v}_3, \mathbf{q}_1 \rangle \\ &= 0 \end{aligned}$$

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$$\tilde{\mathbf{q}}_3 = \mathbf{v}_3 - \langle \mathbf{v}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{v}_3, \mathbf{q}_2 \rangle \mathbf{q}_2$$

Verify that  $\tilde{\mathbf{q}}_3$  is perpendicular to  $\mathbf{q}_1$  and  $\mathbf{q}_2$ .

# Gramm-Schmidt: More vectors!

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$$\tilde{\mathbf{q}}_3 = \mathbf{v}_3 - \langle \mathbf{v}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{v}_3, \mathbf{q}_2 \rangle \mathbf{q}_2$$

Verify that  $\tilde{\mathbf{q}}_3$  is perpendicular to  $\mathbf{q}_1$  and  $\mathbf{q}_2$ .

Make it have unit length:

$$\mathbf{q}_3 = \tilde{\mathbf{q}}_3 / \|\tilde{\mathbf{q}}_3\|_2$$

$$\mathbf{v}_3 = \langle \mathbf{v}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 + \langle \mathbf{v}_3, \mathbf{q}_2 \rangle \mathbf{q}_2 + \|\tilde{\mathbf{q}}_3\|_2 \mathbf{q}_3$$

$$r_{13} = \langle \mathbf{q}_1, \mathbf{v}_3 \rangle; \quad r_{23} = \langle \mathbf{q}_2, \mathbf{v}_3 \rangle; \quad r_{33} = \|\tilde{\mathbf{q}}_3\|_2$$

# Gramm Schmidt = $QR$ Factorization

Starting from  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ :

$$\mathbf{v}_1 = r_{11}\mathbf{q}_1$$

$$\mathbf{v}_2 = r_{12}\mathbf{q}_1 + r_{22}\mathbf{q}_2$$

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$$[\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] = [\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3] \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & r_{23} \\ 0 & 0 & r_{33} \end{pmatrix}$$

$$A = [\vec{v}_1, \dots, \vec{v}_3] \quad 18 \times 3 \quad \rightarrow \quad 18 \times 3$$

# Gramm Schmidt = QR Factorization

Starting from  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ :

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \\ 7 & 8 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{bmatrix} 5 \\ 7 \\ 9 \\ 12 \end{bmatrix}$$

$A$   $b$

$$\mathbf{v}_1 = r_{11}\mathbf{q}_1$$

$$\mathbf{v}_2 = r_{12}\mathbf{q}_1 + r_{22}\mathbf{q}_2$$

$$\mathbf{v}_3 = r_{13}\mathbf{q}_1 + r_{23}\mathbf{q}_2 + r_{33}\mathbf{q}_3$$

$$[\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] = [\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3] \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & r_{23} \\ 0 & 0 & r_{33} \end{pmatrix}$$

If  $A = [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]$ ,

$$A = QR$$

$$Q^T Q = I$$

$$A \setminus b \rightarrow x$$

$$\|Ax - b\|_2$$



$$A = QR$$

$$Rx = Q^T b$$



# Quadratic Interpolation

Data points:  $(x_1, y_1), \dots, (x_5, y_5)$ .

Let's find a 'best fit' quadratic polynomial. Ideally, find  $\mathbf{c} = [c_0, c_1, c_2]^T$  such that

$$c_0 + c_1 x_k + c_2 x_k^2 = y_k$$

for each  $k$ .

$$V\mathbf{c} = \begin{pmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ 1 & x_4 & x_4^2 \\ 1 & x_5 & x_5^2 \end{pmatrix} \mathbf{c} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{pmatrix} = \mathbf{y}$$

We'll minimize

$$\|V\mathbf{c} - \mathbf{y}\|_2^2$$

instead.

