

Last class: EM tensor

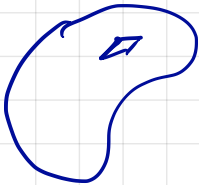
$$F = \begin{bmatrix} 0 & E_1 & E_2 & E_3 \\ -E_1 & 0 & cB_3 & -cB_2 \\ -E_2 & -cB_3 & 0 & cB_1 \\ -E_3 & cB_2 & -cB_1 & 0 \end{bmatrix}$$

$$\frac{dP}{dt} = qGFV$$

$$L^* \hat{F} L = F$$

$$\tilde{F}(x, y) = x^T F y$$

$$\tilde{F}(x, y) = -\tilde{F}(y, x)$$



To this point we have not used the notation

$$\vec{E} = \int_{\mathbb{R}^3} \vec{E}_s(x-y) \rho(y) dy \quad \vec{E}_s = \frac{1}{4\pi\epsilon_0} \frac{1}{|x|^2} \frac{x}{|x|}$$

Next goal: "derive" Maxwell's equations.

Notation:

$\Lambda^0$  functions on spacetime

$\Lambda^1$  covector fields on spacetime ( $\omega(x) = [\omega_0(x), \dots, \omega_3(x)]$ )

$$d: \Lambda^0 \rightarrow \Lambda^1$$

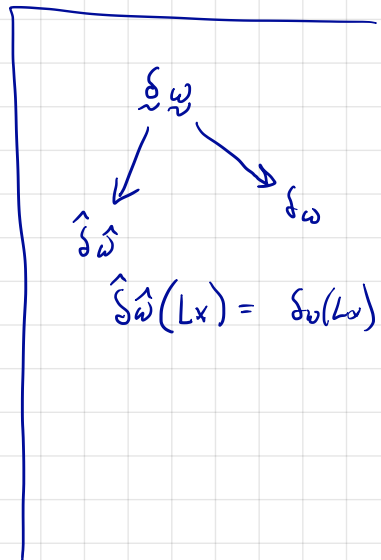
In coords,  $df = [d_0 f, \dots, d_3 f]$

It has a companion

$$\delta: \Lambda^1 \rightarrow \Lambda^0$$

$$\delta\omega = \partial_0\omega_0 - \partial_1\omega_1 - \partial_2\omega_2 - \partial_3\omega_3$$

$$\omega \rightarrow V \rightarrow \text{Div} \cdot V = \delta\omega$$



Exercise:

$$\hat{\delta} \hat{\omega} = \delta \omega$$

$$\delta d f = \square f$$

$\Lambda^1$ : at each  $x$  is a map  $\omega: V \rightarrow \mathbb{R}$ .

$\Lambda^2$ : at each  $x$  is a map  $F: V \times V \rightarrow \mathbb{R}$ ,

bilinear,  $F(V, W) = -F(W, V)$ .

(e.g. the E-M field). We can rep. by an antisymmetric matrix.

$\Lambda^3, \Lambda^4$  as well.

And each of these is meant to be integrated

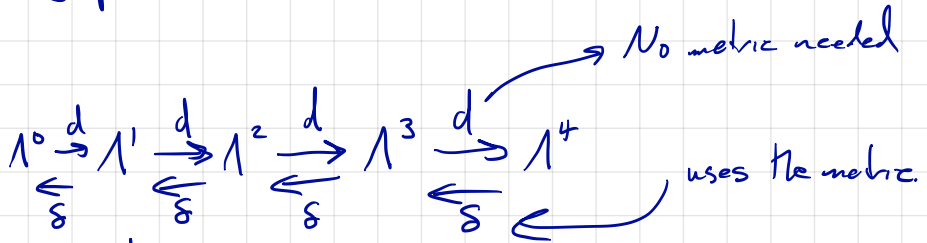
( $\Lambda^1$  over lines,  $\Lambda^2$  over 2-surfaces, etc).



$$\int_a^b \mathcal{L}(\alpha'(s)) ds$$

is independent of param.,  
but depends on direction.

# Big picture



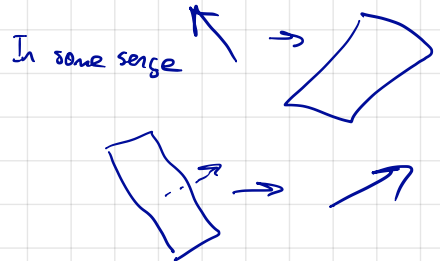
we've seen this

Moreover  $d^2 = 0$

we'll visit this for Maxwell

Hodge  $*$   $\quad * : \Lambda^i \rightarrow \Lambda^{4-i}$

$$\begin{aligned}
 * : \Lambda^0 &\rightarrow \Lambda^4 \\
 &: \Lambda^1 \rightarrow \Lambda^3 \\
 &: \Lambda^2 \rightarrow \Lambda^2 \\
 &: \Lambda^3 \rightarrow \Lambda^1 \\
 &: \Lambda^4 \rightarrow \Lambda^0
 \end{aligned}$$



$$\begin{aligned}
 \delta &= * d * & \text{e.g. } \Lambda^2 &\rightarrow \Lambda^2 \rightarrow \Lambda^3 \rightarrow \Lambda^1 \\
 (\text{so } \delta^2 &= 0) & \Lambda^1 &\rightarrow \Lambda^3 \rightarrow \Lambda^4 \rightarrow \Lambda^0
 \end{aligned}$$

But I'm going to try to avoid discussing  $\Lambda^3, \Lambda^4$   
 ( $\Lambda^0, \Lambda^1, \Lambda^2$  can be rep in terms of matrices, vectors)

$$\Lambda^0 \xrightleftharpoons[\delta]{d} \Lambda^1 \quad \delta d = 0$$

$$\Lambda^1 \xrightleftharpoons[\delta]{d} \Lambda^2 \quad -\delta d = \mathcal{M} \rightarrow \text{maxwell operator.}$$

So who is  $d$ ,  $\delta$ ?

$$\omega = [\omega_0, \omega_1, \omega_2, \omega_3]$$

$$(d\omega)_{ij} = \partial_i \omega_j - \partial_j \omega_i$$

Exercise  $L^{\pm} \hat{d}\omega L = d\omega$  ( $d\omega$  transforms like a 2-form)

Exercise  $d^2: \Lambda^0 \rightarrow \Lambda^2 = 0$

This is a deep generalization of  $\nabla_x(\nabla f) = 0$

$$\text{div}(\nabla_x V) = 0$$

To describe  $S$  I need some notation.

An antisymmetric  $4 \times 4$  matrix has 6 independent entries.

$$\text{Given } R = [R_1, R_2, R_3]$$

$$S = [S_1, S_2, S_3]$$

$$\mathcal{F}(R, S) = \begin{bmatrix} 0 & R_1 & R_2 & R_3 \\ -R_1 & 0 & S_3 & -S_2 \\ -R_2 & -S_3 & 0 & S_1 \\ -R_3 & S_2 & -S_1 & 0 \end{bmatrix}$$

Gives us a way to talk about them.

$$\text{e.g. } F = \mathcal{F}(E, -cB)$$

$$\text{Exercise: if } \omega = [\omega_0, \vec{\omega}]$$

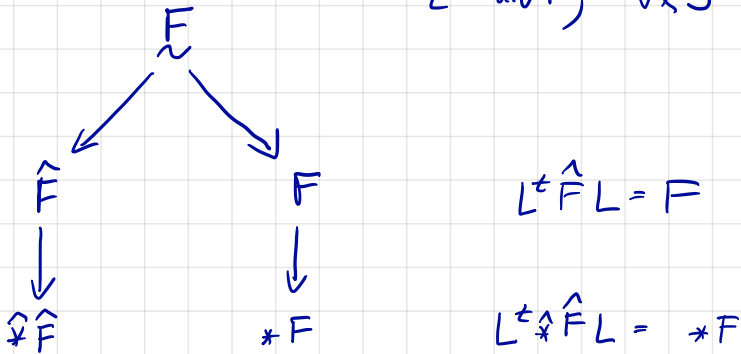
$$d\omega = \mathcal{F}(\partial_0 \vec{\omega} - \nabla \omega_0, \nabla \times \vec{\omega})$$

$$*: \Lambda^2 \rightarrow \Lambda^2$$

$$* \mathcal{F}(R, S) = \mathcal{F}(S, -R)$$

$$* d \mathcal{F}(R, S) = [\operatorname{div} S, -\nabla \times R + \partial_0 S]$$

$$\begin{aligned} * d * \mathcal{F}(R, S) &= * d \mathcal{F}(S, -R) \\ &= [-\operatorname{div} R, -\nabla \times S - \partial_0 R] \end{aligned}$$



( $* \tilde{E}$  defined by  $*F$ )  
 (well defined if  $L^t * \hat{F} L = *F$ )

Much harder  $*dF$  transforms like a 1-form.

We define  $\mathcal{M}: \Lambda^1 \rightarrow \Lambda^1$

$$\mathcal{M} = -\delta d$$

Exercise:  $-\delta d \omega = \square \omega - d \delta \omega$

where  $\square \omega = (\square \omega_1, \square \omega_2)$ .

Fact:  $\hat{M} \hat{\omega} L = \mathcal{M} \omega$  ( $\mathcal{M} \omega$  transforms as a 1-form)



$$\phi_S = \frac{1}{4\pi\epsilon_0 |x|}$$

$$-\nabla\phi_S = E_S$$

$$\phi(x) = \int \phi_S(x-y) \rho(y) dy$$

$$-\nabla\phi = \int E_S(x-y) \rho(y) dy = E$$

$$-\Delta\phi = \int \operatorname{div} E_S \rho(y) dy$$

$$= \frac{1}{\epsilon_0} \rho$$

$$d\omega = \mathcal{F}(\partial_0 \vec{\omega} - \nabla \omega_0, \nabla \times \vec{\omega})$$

$$\omega = [\phi, 0]$$

$$d\omega = \mathcal{F}(-\nabla\phi, 0) = \mathcal{F}(E, 0)$$

in my case  $\boxed{d\omega = F}$

$$d\omega = \mathcal{F}(E, -cB)$$

$$-\delta d\omega = \square\omega - d\delta\omega \overset{\rightarrow}{=} 0$$

$$\delta\omega = \partial_\alpha\omega_\alpha - \text{div}\vec{\omega} = 0$$

$$= (-\Delta\phi, 0)$$

$$= (-\text{div}\nabla\phi, 0)$$

$$= \frac{1}{c\epsilon_0} (c\rho, 0)$$

current density vector:

it's covector version

$$\begin{bmatrix} c\rho \\ j \end{bmatrix} \begin{matrix} \nearrow c/m^3 \cdot s \\ \rightarrow c/m^2 \cdot s \\ \text{charge flux} \end{matrix}$$

So in any frame, not just at rest,  
 $\uparrow$  changes

$$M\omega = \frac{1}{c\epsilon_0} (c\rho, -j)$$

These are Maxwell's equations relating  $\omega$  and charge density.

They hold in general, not just electrostatics.

$$d\omega = \mathcal{F}_1(E, -cB) \quad \text{by det of } E, B.$$

$$*d\omega = \mathcal{F}_1(-cB, -E)$$

$$*d*d\omega = (-\operatorname{div} E, c\nabla \times B - \partial_0 S)$$

$$- *d*d\omega = (\operatorname{div} E, -c\nabla \times B + \partial_0 E)$$

$$*d \mathcal{F}_1(R, S) = [\operatorname{div} S, -\nabla \times R + \partial_0 S]$$

$$\text{So } \textcircled{1} \quad \operatorname{div} E = \frac{1}{\epsilon_0} \rho \quad (\text{Gauss' Law})$$

$$-\nabla \times B + \partial_0 E = -\frac{1}{c\epsilon_0} j$$

$$\textcircled{2} \quad \nabla \times B = \underbrace{\frac{1}{c^2 \epsilon_0}}_{\mu_0} j - \underbrace{\frac{1}{c}}_{\partial_0} \partial_0 E \quad (\text{Ampere's equation with Maxwell's addition})$$

$$\text{Exercise: } *d*d\omega = 0 \quad (\text{another face of } d^2=0)$$

$$*d \mathcal{F}_1(E, -cB) = [-c\operatorname{div} B, -\nabla \times E + \partial_0(-cB)]$$

$$\textcircled{3} \quad \operatorname{div} B = 0 \quad (\text{no magnetic sources})$$

$$\textcircled{4} \quad \partial_0 B + \nabla \times E = 0 \quad (\text{Faraday's Law of Induction})$$

$$\begin{aligned}
 \delta \mathcal{F}(R, S) &= *d\mathcal{F}(S, -R) \\
 &= [\operatorname{div}(-R), -\partial_0 R - \nabla_x S] \\
 &= -[\operatorname{div} R, \partial_0 R + \nabla_x S]
 \end{aligned}$$

$$\delta [\omega_0, \vec{\omega}] = \partial_0 \omega_0 - \operatorname{div} \vec{\omega}$$

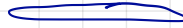
Exercise:  $\delta^2 = 0$

$$\text{But } \mathcal{M} \omega = -\delta d\omega = \frac{1}{c\epsilon_0} [c\rho, -j]$$

$$\delta \mathcal{M} = -\delta^2 d\omega = 0$$

$$J = \begin{bmatrix} c\rho \\ j \end{bmatrix}$$

$\operatorname{Div} J = 0 \rightarrow$  conservation of charge.



$\int_{\Omega} \rho \leftarrow$  observed  
charge  
density

Gauge freedom.

$$\text{Suppose } \mathcal{M}\omega = \frac{1}{c\epsilon_0} \mathbf{j}$$

$$\tilde{\omega} = \omega + df$$

$$\begin{aligned}\mathcal{M}\tilde{\omega} &= -Sd(\omega + df) \\ &= -Sd\omega + -Sd^2f \\ &= \frac{1}{c\epsilon_0} \mathbf{j} + 0.\end{aligned}$$

Moreover,  $d\tilde{\omega} = d\omega + d^2f = d\omega$  so same EM field.

These are two faces of the same solution of Maxwell's equations and reflect a kind of coordinate change.

$$\text{Now } \mathcal{M}\omega = \square\omega - dS\omega$$

$$\text{If we can arrange } S\omega \equiv 0 \quad (\partial_0\omega_0 - \text{div } \vec{\omega} = 0)$$

then Maxwell's equations reduce to wave equations

Is this even possible?

$$\vec{\omega} = \omega + df$$

$$\delta \vec{\omega} = \delta \omega + \delta df$$

$$\square f = -\delta \omega$$

So  $f$  needs to solve an inhomogeneous wave eq.

[We didn't discuss, but solution always exists, with arbitrary initial data]

I.e. if you can find one, you can find one with  $\delta \vec{\omega} = 0$ .

This choice of gauge is called Lorenz gauge.

Start with arbitrary  $\omega$ .  $\partial_0 \omega$

Pick  $f$  a function of space alone,

$$-\Delta f = -\partial_0 \omega_0 + \text{div } \vec{\omega}$$

So  $\delta df = -\delta \omega$  at  $t=0$ .