

Now 3 space dimensions.

We'll assume coordinate transformations are affine (so non-acceleration is preserved).

We'll assume that if one observer says \underline{E} and \underline{F} lie on the path of a non-accelerating particle traveling at the speed of light, all observers say so.

$$\begin{aligned} \underline{E} &= (t_0, x_0) & \rightarrow & \quad |c\Delta t| = |\Delta x| \\ \underline{F} &= (t_1, x_1) & & \quad |c\Delta t'| = |\Delta x'| \end{aligned}$$

Let us deal with linear case first

$$\begin{pmatrix} t' \\ x' \end{pmatrix} = A \begin{pmatrix} t \\ x \end{pmatrix}$$

$$\downarrow \\ c^{-1} L c$$

$$c = \begin{bmatrix} c & 1 \\ 1 & 1 \end{bmatrix}$$

F lies on path of a photon from O:

$$c|t| = |x|$$

$$c^2(t)^2 = |x|^2$$

$$(CF)^T G CF = 0 \quad G = \begin{bmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{bmatrix}$$

We require

$$(CAF)^T G CAF = 0$$

whenever $(CF)^T G CF = 0$

$$A = C^T L C$$

$$(CF)^T L^T G L CF = 0$$

whenever

I.e.

$$X^T L^T G L X = 0 \quad \text{whenever}$$

$$X^T G X = 0 \quad (X = CF)$$

$$\text{e.g.: } X = \begin{bmatrix} 1 \\ U \end{bmatrix} \quad |U|^2 = 1$$

$$L^T G L = \begin{bmatrix} \alpha & a \\ a & \delta \end{bmatrix} \quad \text{for some } \alpha, a, \delta \quad S \stackrel{T}{=} S \\ (\text{Why?})$$

$$\begin{aligned} X^T L^T G L X &= \alpha + 2a \cdot U + U^T \delta U \\ &= U^T (\alpha I) U + 2a \cdot U + U^T \delta U \\ &= U^T [\alpha I + \delta] U + 2a U \end{aligned}$$

$$\text{So } U^T [\alpha I + \delta] U + 2a \cdot U = 0 \quad \text{if } |U| = 1$$

$$U \rightarrow -U \quad U^T [\alpha I + \delta] U - 2a \cdot U = 0 \quad \text{also}$$

So $a \cdot U = 0$ for all unit vectors U ,

and therefore all vectors. So $a \cdot a = 0$ and $a = 0$.

Also:

$$U^T [\alpha I + S] U = 0 \text{ for all unit vectors } U.$$

But any $W = \lambda U$, U a unit vector, so

$$W^T [\alpha I + S] W = \lambda^2 U^T [\alpha I + S] U = 0$$

for all vectors $W \in \mathbb{R}^3$.

$B(W, Y) = W^T [\alpha I + S] Y$ is bilinear and agrees on diagonal with 0. So $W^T [\alpha I + S] Y = 0$ for all vectors W, Y . So $\alpha I + S = 0$ (use e_i, e_j).

$$\text{So } S = -\alpha I$$

We conclude: $a = 0$ ($a \cdot a = 0!$)

$$S + \alpha I = 0, \quad S = -\alpha I \quad (\text{polarization})$$

$$L^T G L = \alpha \begin{bmatrix} 1 & \\ & -I \end{bmatrix} = \alpha G.$$

Now $L = \begin{bmatrix} \gamma & - \\ 1 & * \end{bmatrix}$

$$L \begin{bmatrix} ct \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} \gamma \\ 1 \\ \vdots \\ 1 \end{bmatrix} ct$$

↖ path of O.

$$ct' = \gamma ct$$

↑ encodes time dilation.

Relativity hypothesis: time dilation between the two coordinate systems is the same.

$$L^{-1} = \begin{bmatrix} \gamma & - \\ 1 & * \end{bmatrix} \text{ also, for other stuff.}$$

$$L^T G L = \alpha G \Rightarrow$$

$$L^T = \alpha G L^{-1} G$$

$$G \begin{bmatrix} \gamma \\ * \end{bmatrix} = \begin{bmatrix} \gamma \\ -* \end{bmatrix}$$

↑
upper left
entry is γ

↑
upper left entry is $\alpha \gamma$

$$\text{So } \alpha = 1.$$

We assumed:

- 1) Linear
- 2) path of photons preserved
- 3) relativity of time dilation

$$\begin{bmatrix} t \\ x' \end{bmatrix} = A \begin{bmatrix} t \\ x \end{bmatrix}$$

$$A = \mathcal{O}^{-1} L \mathcal{O}$$

$$L^T G L = G$$

↑
These are the
(natural) Lorentz transformations.

↑
physical Lorentz trans.

$O(1,3)$: subgroup of $GL(4, \mathbb{R})$ $L^T G L = G$.

Exercise: The affine transformations are

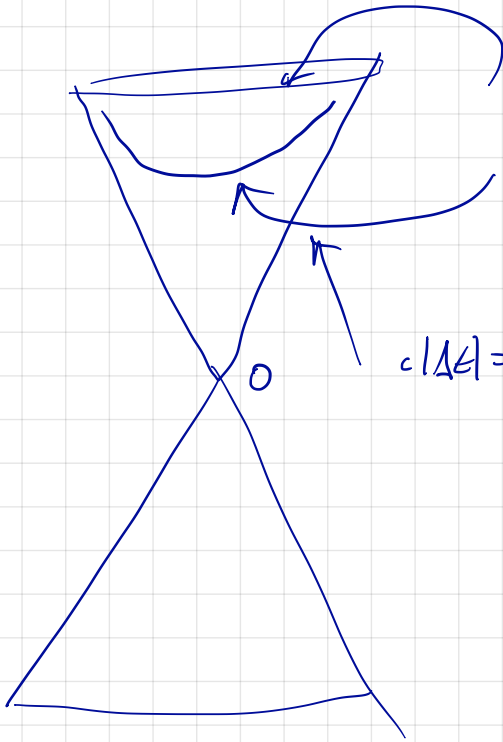
$$C^{-1} L C + Z \quad \begin{array}{l} Z \in \mathbb{R}^4 \\ L \in O(1,3) \end{array}$$

As in 2-d case, interval:

$$X = C(F - E)$$

$$\text{Int}(E, F) = X^T G X \quad (c\Delta t)^2 - (\Delta x)^2 - (\Delta y)^2 - (\Delta z)^2$$

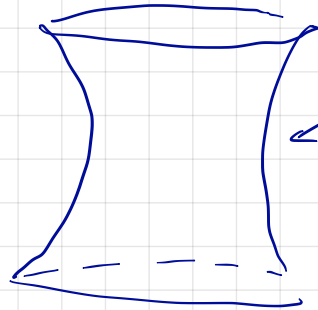
physical Lorentz transformations preserve interval in
natural coordinates



interval positive \curvearrowright

interval = x^2 (proper time diff is $\frac{x}{c}$)

$c|\Delta t| = |\Delta \vec{x}|$, interval is 0



hyperboloid for $\text{int}(0, P) = -1$

Call the things that are space distance 1 from origin

Def: The future light cone of origin is set of events $E = \begin{bmatrix} t \\ x \end{bmatrix}$ with $\text{Int}(0, E) = 0$ and $t > 0$.

Def: A ^{4x4} matrix L is a Lorentz transform, if

$$L^T G L = G.$$

- a) It is orthochronous if in addition it sends the future light cone of the origin to itself.
- b) It is proper if $\det(L) = 1$.
- c) It is restricted if both proper + orthochronous.

a) $O^+(1, 3)$

b) $SO(1, 3)$

c) $SO^+(1, 3)$

Lemma: Let $L \in O(1,3)$. If L is orthochronous
 then

$$L^0_0 > 0. \quad (L^0_0; \text{I'll explain why your book does this later})$$

$$\begin{aligned} \text{Pf: } L \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix} &= L \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + L \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} c\epsilon_0 \\ * \\ * \\ * \end{bmatrix} + \begin{bmatrix} c\epsilon_1 \\ * \\ * \\ * \end{bmatrix} \end{aligned}$$

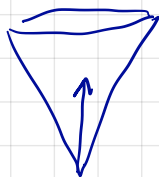
$$\text{with } \epsilon_0, \epsilon_1 > 0. \quad \text{But } L \begin{pmatrix} 2 \\ \vdots \\ 0 \end{pmatrix} = \begin{pmatrix} 2L^0_0 \\ * \end{pmatrix}.$$

$$\text{So } 2L^0_0 = c(\epsilon_0 + \epsilon_1) > 0.$$

In fact, the converse is true; we'll wait a bit for this. But in the near future, o.c. $\Leftrightarrow L^0_0 > 0$ is true.

Meaning of L^0_0 :

$$L \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} L^0_0 \\ L^1_0 \\ L^2_0 \\ L^3_0 \end{bmatrix}$$



↑ true coord of image of $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$.
 natural

e.g.

$$R_{\gamma} = \begin{bmatrix} c & s & 0 \\ 0 & c & 0 \\ 0 & 0 & I \end{bmatrix}$$

(boost in $x-t$ plane)

$$c > 0, \quad \det \text{ is } (c^2 - s^2) \cdot 1^2 = 1.$$

e.g. $\begin{bmatrix} 1 & 0 \\ 0 & H \end{bmatrix} \quad H \in \text{SO}(3)$

$$\begin{bmatrix} 1 & 0 \\ 0 & H^T \end{bmatrix} \begin{bmatrix} +1 & 0 \\ 0 & -I \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & H \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 \\ 0 & H^T \end{bmatrix} \begin{bmatrix} +1 & 0 \\ 0 & -I \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -I \end{bmatrix} \quad \checkmark$$

$$\det \text{ is } 1 \cdot \det(H) = 1$$

$$1 > 0,$$

e.g.

v any unit vector in \mathbb{R}^3

K any element of $SO(3)$, $Ke_1 = v$

$$\begin{bmatrix} v & | & \dots & | \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 \\ 0 & K \end{bmatrix} \mathcal{L}_4 \begin{bmatrix} 1 & 0 \\ 0 & K^T \end{bmatrix}$$

exercise: $\forall w \in \mathbb{R}^3$, $w \cdot v = 0$

$L \begin{bmatrix} 0 \\ w \end{bmatrix} = 0$. As for v , this is a boost in the v - z plane.

More generally:

$$\begin{pmatrix} 1 & 0 \\ 0 & H \end{pmatrix} \mathcal{L}_4 \begin{bmatrix} 1 & 0 \\ 0 & K^T \end{bmatrix} \quad H, K \in SO(3)$$

Exercise (next HW?)

$$L \in SO^+(1,3) \Leftrightarrow L = \begin{bmatrix} 1 & \\ & H \end{bmatrix} \alpha_\mu \begin{bmatrix} 1 & \\ & K^T \end{bmatrix}$$

for some $\alpha \in \mathbb{R}$, $H \in BO(3)$, $K \in SO(3)$.

They are compositions of spatial rotations and boosts.

(4)- vectors