

E = (t, x) physical coordinates (ct,x) natural woordinates (all entres units of lensth) $\begin{bmatrix} \mathbf{c} \mathbf{c} \\ \mathbf{x} \end{bmatrix} = \begin{bmatrix} \mathbf{c} \mathbf{v} \\ \mathbf{o} \mathbf{T} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{x} \end{bmatrix} \mathbf{C}$ Given two points $(\epsilon_{i,x_i}) = F$ • (t., x.) = E I can construct a gumbity associated with the puir called the interval separations they 1) $\chi = CF - CE = C(F - E)$ (displacenest from E to F in natural units $2) \quad G = \begin{bmatrix} +1 & 0 \\ 0 & -1 \end{bmatrix}$ Cm be +,-, 0. If $F = \begin{bmatrix} \Delta t \\ \Delta x \end{bmatrix}$, $I_{A} + (F, X) = (c\Delta t)^2 - (\Delta x)^2$ units of length² $Iut(E,F) = X^TGX$

Given nother observer O' what does O'

assu as the interval?





 $CE' = L_{-v}CE$ $\chi' = C(E'-F') = L_{-v}C(E-F)$

= L_v X

 $(X')^{T}_{G} X = X^{T} L^{T}_{-v} G L_{-v} X$

 $(X')^{T}GX = X^{T}L^{T}GL_{-v}X$ $\begin{pmatrix} C - S \\ -S C \end{pmatrix} \begin{pmatrix} I & 0 \\ 0 - I \end{pmatrix} \begin{pmatrix} C - S \\ -S & C \end{pmatrix} = \begin{pmatrix} C - S \\ -S C \end{pmatrix} \begin{pmatrix} c - S \\ -S &$ \leq $= \begin{pmatrix} C^2 - S^2 & O \\ O & -C^2 + S^2 \end{pmatrix}$ $= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ $= X^T G X.$

The interval between two points, in any of Nexe coordinate systems is $f(z) = C^{-1}LC_{2} + T$ $(c\Lambda t)^2 - (\Lambda t)^2$ Of course, it is presend by trustachas as a ell This is the Sudmental quality of 2.2 specetime Not replaces the solion of distance in Eveliden georety Let us suppose E is onigen.

Where and points with where = 1 from E = 2?

Here we some. Start with (x)= ()=X. Now sand through dp. $\begin{bmatrix} c & s \\ s & c \end{bmatrix} \begin{bmatrix} i \\ s \end{bmatrix} = \begin{bmatrix} c \\ s \end{bmatrix}$

Recall: C2-52=1



	(ch)	1-1	16-	1	1
NC missed Some:	$\begin{pmatrix} z \\ x \end{pmatrix} =$	$\left(\circ \right)$	a 1010	Mes on very	¢.



The transform trans we we working with only take the upper brands to the upper branch etc. What about -1? Shut un the [0] Now sad through Ip to got [5] 5- 6--1 620 50 Always stays on vight site. Smilely for left had branch. -ct = K, stoud K^2 In general, x=X, interval -XZ X=-X indexal - K² ct = - K intern - X²

So what does the interval measure? $E = (t, x) \quad c \in 2 - x^2 = X^2 > 0, \quad t > 0$ $f_{rck} \neq f_{rnh}(\psi) = \frac{x}{ct}$ Exocise: $\mathcal{L}_{\gamma}\begin{pmatrix}c \\ \chi\end{pmatrix} = \begin{pmatrix} K\\ 0 \end{pmatrix}$ • (<u>ද</u>, d) In a frame where Q and E have the same space coordinate, K/c is the trune difference from Q to E. In any other frame, the time difference is at last this big: time dilation the companion of length contraction] it will be 8K Smilurif ECO. We call (This) the "proper time" separations Ond E

 $(t)^{2} + \chi^{2} = -\chi^{2} < 0 = \chi^{2} < 0$ $\frac{den}{den} \frac{de}{de} = \frac{ct}{x}$ $exercise: \quad x = \begin{bmatrix} ct \\ x \end{bmatrix} = \begin{bmatrix} 0 \\ x \end{bmatrix}$

K is the distance between Q ad E in a coordinate system in which O and E are simultaneous.

We call this the proper distance between O and E.

The full set of trasformations of R² that preserve the interval is known as the Poincard group.

Those that preserve the origin are called the Lorentz group. O(1,1)

The are some weindos: $A = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \qquad (tme vertlection)$ $\begin{bmatrix} -i & 3 \\ 0 & i \end{bmatrix} \begin{bmatrix} ot \\ x \end{bmatrix} = \begin{bmatrix} -ot \\ x \end{bmatrix}$ $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ space reflection. We can vale these out via def(A) = 1. SO(1,1). But this still allows [-1 0] (space + the veflection) $\langle l \rangle \longrightarrow \langle l \rangle$ SO'((1) for taking future to Same

Now 3 space dimensions.

We'll assure coordinate transformations are affine (50 non-acceleration is preserved).

We'll assume that if one observer says E and E

lie on the puth of a non accelering porticle

truveling at the speed of holid, all observes

Say 50.

 $E = (E_{j,X_{o}}) \longrightarrow [cAt] = |\Delta x|$ $F = (E_{j,X_{o}})$

Let us deal with linear case first $\begin{pmatrix} t' \\ \star' \end{pmatrix} = A \begin{pmatrix} t \\ \star \end{pmatrix}$ CILC $C = \begin{bmatrix} c \\ f \end{bmatrix}$

F lies on pale of a ploten from O:

 $c|\Delta t| = |x|$ $c^{2}(1E)^{2} = |x|^{2}$ $G = \begin{bmatrix} I \\ -1 \\ -1 \end{bmatrix}$ $(CF)^{\mathsf{T}} \mathsf{G} \mathsf{C} \mathsf{F} = \mathsf{O}$ Ve reque $(CAF)^{T}G CAF = O$ 28: phys 30 ayeage Nover (CF)⁷6-CF=0 redo: sen CFILGLCF = O Where A= CLC XIGLX=0 whenave I.e. $X^T G X = O$

Full spacetime:

 $G = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ spuceture metric.

Them between $(E_1, K_2, T_1, Z_1) = E_1$ (E_2, K_2, Y_2, Z_2) = E_2

 $\int c(t_2-t_1) \left[- (x_2-x_1)^2 - (y_2-y_1)^2 - (z_2-z_1)^2 \right]$

 $(E_2 - E_1)^{\overline{c}} C^{T} G C (E_2 - E_1)$

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A Lorentz transformation is a liner nop L